

## Types of Schaum's outline

### ② Co-ordinate Transformation

Let for two reference frame of the co-ordinate as a

$$\begin{aligned} \bar{x}^1 &= \bar{x}^1 (x^1, x^2, \dots, x^N) \\ \bar{x}^2 &= \bar{x}^2 (x^1, x^2, \dots, x^N) \\ &\vdots \\ \bar{x}^N &= \bar{x}^N (x^1, x^2, \dots, x^N) \end{aligned} \quad \left. \vphantom{\begin{aligned} \bar{x}^1 \\ \bar{x}^2 \\ \vdots \\ \bar{x}^N \end{aligned}} \right\} \text{--- (1)}$$

by briefly.

$$\bar{x}^k = \bar{x}^k (x^1, x^2, \dots, x^N) \quad k=1, 2, \dots, N \quad \text{--- (2)}$$

For single-valued, continuous derivation. The

inversely be written as

$$x^k = x^k (\bar{x}^1, \bar{x}^2, \dots, \bar{x}^N), \quad k=1, 2, \dots, N \quad \text{--- (3)}$$

The relation (2) or (3) define a transformation of coordinates from one space to another.

#### ④ Contravariant and Co-variant vector

Let  $N$  quantities  $A^1, A^2, \dots, A^N$  in  $(x^1, x^2, \dots, x^N)$  system and  $\bar{A}^1, \bar{A}^2, \dots, \bar{A}^N$  of  $(\bar{x}^1, \bar{x}^2, \dots, \bar{x}^N)$  system. Then by transformation eqns in summarised method

$$\bar{A}^p = \sum_{q=1}^N \frac{\partial \bar{x}^p}{\partial x^q} A^q, \quad \text{where } p=1, 2, \dots, N$$

Conventionally written as

$$\bar{A}^p = \frac{\partial \bar{x}^p}{\partial x^q} A^q.$$

This is the components of a contravariant vector or contravariant tensor of the 1st rank or first order. (see Problem 7.33 & 7.34)

or otherwise  $A_1, A_2, \dots, A_N$  of  $N$  quantities of system  $(x^1, x^2, \dots, x^N)$  and  $\bar{A}_1, \bar{A}_2, \dots, \bar{A}_N$  of  $N$  quantities in  $(\bar{x}^1, \bar{x}^2, \dots, \bar{x}^N)$  system. Then transformation eqns as

$$\bar{A}_p = \sum_{q=1}^N \frac{\partial x^q}{\partial \bar{x}^p} A^q, \quad p=1, 2, \dots, N$$

Simply written as

$$\bar{A}_p = \frac{\partial x^q}{\partial \bar{x}^p} A^q$$

known as covariant vector or covariant tensor of the 1st rank or 1st order.

⑤ Contravariant, Covariant, and Mixed Tensors :-

Let  $N^2$  quantities  $A^{rs}$  in  $(x^1, x^2, \dots, x^N)$  system &

$\bar{A}^{rs}$  in  $(\bar{x}^1, \bar{x}^2, \dots, \bar{x}^N)$  system

$$\bar{A}^{rs} = \sum_{s=1}^N \sum_{r=1}^N \frac{\partial x^r}{\partial \bar{x}^s} \frac{\partial x^s}{\partial \bar{x}^r} A^{rs}$$

Simply -  $\bar{A}^{rs} = \frac{\partial x^r}{\partial \bar{x}^s} \frac{\partial x^s}{\partial \bar{x}^r} A^{rs}$

Known as Two Contravariant Tensor of 2nd rank or rank of rank two

Any  $\bar{A}_{rs} = \frac{\partial x^r}{\partial \bar{x}^s} \frac{\partial x^s}{\partial \bar{x}^r} A_{rs}$

Covariant tensor of 2nd rank.

&

For Mixed Tensor

$$\bar{A}^r_s = \frac{\partial x^r}{\partial \bar{x}^s} \frac{\partial x^s}{\partial \bar{x}^r} A^r_s$$

For 3rd  $\bar{A}^{rst} = \frac{\partial x^r}{\partial \bar{x}^s} \frac{\partial x^s}{\partial \bar{x}^t} \frac{\partial x^t}{\partial \bar{x}^r} A^{rst}$  , 3rd rank

⑥ Kronecker Delta  $\delta^j_k$  if  $j \neq k$

$$\delta^j_k = \begin{cases} 0 & \text{if } j \neq k \\ 1 & \text{if } j = k \end{cases}$$

⑦ Tensor of rank greater than two, Tensor

Any mixed tensor  $A_{kl}^{rst}$   $\rightarrow$  Rank - 5  
 Contravariant - order - 3  
 Covariant order - 2

Can be transformed due to the relation

$$A_{ij}^{pqr} = \frac{\partial x^p}{\partial x^i} \frac{\partial x^q}{\partial x^j} \frac{\partial x^r}{\partial x^k} \frac{\partial x^l}{\partial x^m} A_{kl}^{rst}$$

⑧ Scalar or Invariant

$\phi = \bar{\phi} A$  scalar or invariant known as  
 Tensor of rank zero

⑨ Tensor field - In any N-dimensional space define tensor may vector or scalar; It should be noted that a tensor or tensor field is not just the set of its components in one special coordinate system but all the possible sets under any transformation of coordinate.

10) Symmetric Tensor

No change due to two covariant indices or contravariant indices  $m \rightarrow$

$$A_{qs} = A_{sq}$$

$$A^{qs} = A^{sq}$$

All are symmetric tensors.

11) Anti symmetric Tensors

$$A_{qs} = -A_{sq}$$

12) operation apply

(a) Addition

$$C_q = A_q + B_q$$

(Commutative & Associative)

same rank and type

(b) Subtraction

$$D_q = A_q - B_q$$

(c) outer multiplication

$$A_{qs} B_{rs} = C_{qrs}$$

Summation of contravariant & summation covariant

④ Inner Product :-

As outer product

$$A_{m \times p} \otimes B_{p \times s}$$

Putting  $q = s$ ,

$$A_{m \times p} \otimes B_{p \times s}, \text{ putting } p = s$$

Another product

$$A_{m \times p} \otimes B_{p \times s}$$

another inner product is obtained.

⑤ Quotient law :- Suppose it is not known whether a quantity  $X$  is a tensor or not. If an inner product of  $X$  with an arbitrary tensor is itself a tensor, then  $X$  is also a tensor. This is known as quotient law.

⑬ Matrix

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

Compact form  $[a_{pq}]$ ,  $p = 1 \dots m$ ,  $q = 1 \dots n$

# ① Line Element and Matrix Tensor

Line element

$$ds^2 = dx^2 + dy^2 + dz^2$$

$$= \sum_{p=1}^3 \sum_{q=1}^3 g_{pq} dx^p dx^q$$

(Curvilinear co-ord)

Known as Three 3D Euclidean space

generally for N - dimension

$$ds^2 = \sum_{p=1}^N \sum_{q=1}^N g_{pq} dx^p dx^q$$

Conventionally written as

$$ds = g_{pq} dx^p dx^q$$

Transformation of co-ordinates from  $x$  to  $u^j = x^k$

such that space. The metric tensor into

Transformation into

$$(du^1)^2 + (du^2)^2 + \dots + (du^N)^2$$
$$dx^k dx^k$$

This type coordinate called

$N$ -dimensional Euclidean space; in general known as "Riemannian"

(15) Congruate or Reciprocal Tensor

Let  $g = |g_{pq}|$  denote the determinant with elements  $g_{pq}$  and suppose  $g \neq 0$ , denoted by  $g^{pq}$  as  $g^{ij} = \frac{1}{g}$

$$g^{pq} = \frac{\text{co-factor of } g_{pq}}{g}$$

This  $g^{pq}$  is a symmetric contravariant tensor of rank two called the congruate or reciprocal tensor of  $g_{pq}$ . Valid for

$$g^{pq} g_{rs} = \delta^p_r \quad ||$$



### (16) Associated Tensors

All tensors obtained from a given tensor by forming inner products with the metric tensor and its conjugate are called associated tensors of the given tensor.

eg.  $A^m$  and  $A_m$  are associated tensors, the first are contravariant & 2nd covariant components. The relation between them is given

$$\text{by } A_p = g_{pq} A^q \text{ or } A^p = g^{pq} A_q$$

For the Cartesian coordinate system

$$g_{pq} = 1 \text{ if } p = q \\ = 0 \text{ if } p \neq q$$

so that  $A_p = A^p$ , no difference between contravariant & covariant components.

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(17) Christoffel's Symbols

The following symbols

$$[\rho\sigma, \gamma] = \frac{1}{2} \left( \frac{\partial g_{\rho\sigma}}{\partial x^\gamma} + \frac{\partial g_{\rho\gamma}}{\partial x^\sigma} - \frac{\partial g_{\gamma\rho}}{\partial x^\sigma} \right)$$

$$\left\{ \begin{matrix} \sigma \\ \rho\sigma \end{matrix} \right\} = g^{\sigma\gamma} [\rho\sigma, \gamma]$$

Known as Christoffel's Symbols of the first and 2nd kind. The 2nd kind  $\left\{ \begin{matrix} \sigma \\ \rho\sigma \end{matrix} \right\}$  are  $\left\{ \begin{matrix} \sigma \\ \rho\sigma \end{matrix} \right\}$  and  $\Gamma_{\rho\sigma}^\sigma$

(18) Transformation law of Christoffel Symbols

Suppose two co-ordinate  $\bar{x}^k$  then

$$[\bar{j}\bar{k}, \bar{m}] = [\rho\sigma, \gamma] \frac{\partial x^\rho}{\partial \bar{x}^j} \frac{\partial x^\sigma}{\partial \bar{x}^k} \frac{\partial x^\gamma}{\partial \bar{x}^m} + g_{\rho\sigma} \frac{\partial x^\rho}{\partial \bar{x}^m} \frac{\partial^2 x^\sigma}{\partial \bar{x}^j \partial \bar{x}^k}$$

$$\left\{ \begin{matrix} \bar{n} \\ \bar{j}\bar{k} \end{matrix} \right\} = \left\{ \begin{matrix} \sigma \\ \rho\sigma \end{matrix} \right\} \frac{\partial \bar{x}^\sigma}{\partial x^\rho} \frac{\partial x^\rho}{\partial \bar{x}^j} \frac{\partial x^\rho}{\partial \bar{x}^k} + \frac{\partial \bar{x}^\sigma}{\partial x^\rho} \frac{\partial^2 x^\rho}{\partial \bar{x}^j \partial \bar{x}^k}$$

are the laws of transformation of the Christoffel's Symbols showing that they are not tensors unless the terms on the right are zero

## Meaning of Christoffel

However, since  $g_{ik}$  is a tensor, its covariant derivatives can be expressed in terms of regular partial derivatives and Christoffel symbols:

$$g_{ik;l} = \frac{\partial g_{ik}}{\partial x^l} - g_{mk} \Gamma_{il}^m - g^{mn} \Gamma_{nl}^m$$

Rewriting the above expression and then performing permutation in  $i, k$  and  $l$

$$\frac{\partial g_{ik}}{\partial x^l} = g_{mk} \Gamma_{il}^m + g^{mn} \Gamma_{nl}^m$$

$$\frac{\partial g_{kl}}{\partial x^i} = g_{mi} \Gamma_{lk}^m + g^{mn} \Gamma_{li}^m$$

$$-\frac{\partial g_{li}}{\partial x^k} = -g^{mi} \Gamma_{lk}^m - g^{mn} \Gamma_{li}^m$$

Adding these eqns -

$$\frac{\partial g_{ik}}{\partial x^l} + \frac{\partial g_{kl}}{\partial x^i} - \frac{\partial g_{li}}{\partial x^k} =$$

$$2g_{mk} \Gamma_{il}^m$$

$$\therefore 2g_{mk} \Gamma_{il}^m = \Gamma_{ik,l} + \Gamma_{kl,i} - \Gamma_{lik}$$

Rate of change space

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Euclidean Manifold

$$(ds)^2 = (dx^i)^2, \quad i = 1, 2, 3$$

$$= (dx^1)^2 + (dx^2)^2 + (dx^3)^2$$

Riemann matrix

$$ds^2 = g_{ij} dx^i dx^j, \quad g_{ij} = g_{ji}$$

$$\begin{pmatrix} g_{11} & g_{12} & g_{13} \\ g_{21} & g_{22} & g_{23} \\ g_{31} & g_{32} & g_{33} \end{pmatrix} = g_{ij}$$