

Density of distribution in phase space

The use of ensembles in st. mechanics is guided by the following factors \rightarrow

- (1) There is no need to maintain distinction between individual systems as we are only interested in number of systems at any time which would be found in different state that corresponding different phase space.
- (2) The no. of elements in an ensemble is so large that there is a continuous change in this number in passing from one region of phase to another.

The condition of an ensemble at any time can be specified by the density ρ with the phase points are distributed over the phase space named as density of distribution or Probability density of distribution Function.

The density of distribution ρ of the is the function of q and p position coordinates and f -momentum co-ordinate i.e. (q_1, q_2, \dots, q_n) and (p_1, p_2, \dots, p_n) corresponding to 2d axes in phase space.

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The density of distribution is also a function of time because at any time it

$$\rho = \rho(q_1, \dots, q_f; p_1, p_2, \dots, p_f); t \}$$

$$\Rightarrow \rho = \rho(q, p, t)$$

The small volume of the phase space named as Hyper-volume $\delta\Gamma$ of the phase points -

$$\delta\Gamma = \delta q_1 \delta q_2 \dots \delta q_f; \delta p_1 \dots \delta p_f, t$$

The number of systems δN lying in the specified region can be obtained by multiplying the density of distribution and the Hyper-volume in the phase space it

$$\delta N = \rho(q, p, t) \delta q_1 \dots \delta q_f, \delta p_1 \dots \delta p_f$$

$$\therefore \delta N = \rho \delta q_1 \dots \delta q_f \delta p_1 \dots \delta p_f$$

In brief

$$\delta N = \rho \prod_{i=1}^f \delta q_i \delta p_i$$

By integrating over the whole of the phase space

$$N = \int \rho dq_1 \dots dq_f dp_1 \dots dp_f$$

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General discussion of Mean values :-

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The average value of variable u in an ensemble is defined by multiplying each possible u_i by the number n_i of the system in the ensemble which exhibits this value, adding the resultant product for all possible values of the variable u and then dividing this sum by the total number of system in the ensemble.

Let u be the variable which can assume any of the M discrete values.

$$u_1, u_2 \dots u_M$$

with respective probabilities

$$w(u_1) \dots w(u_M)$$

Then mean (or average) value of u is denoted by \bar{u} and is defined by

$$\bar{u} = \frac{w(u_1)u_1 + w(u_2)u_2 + \dots + w(u_M)u_M}{w(u_1) + w(u_2) + \dots + w(u_M)}$$

$$\bar{u} = \frac{\sum_{i=1}^M w(u_i) u_i}{\sum_{i=1}^M w(u_i)}$$

More generally, if $f(u)$ is any function of u then the mean value $f(u)$ is denoted

by

$$\bar{f}(u) = \frac{\sum_{i=1}^M w(u_i) f(u_i)}{\sum_{i=1}^M w(u_i)}$$

This expression can be simplified as unity,

$$\sum_{i=1}^M w(u_i) = w(u_1) + w(u_2) + \dots + w(u_M) = 1$$

$$\therefore \bar{f}(u) = \sum_{i=1}^M w(u_i) f(u_i)$$

If the probability distribution function is continuous in all position and momentum co-ordinates the above eqn \rightarrow

$$\bar{u} = \frac{\int u(q, p) w(q, p) d\Gamma}{\int w(q, p) d\Gamma}$$

where $d\Gamma = dq_1 \dots dq_M, dp_1 \dots dp_M$.

But according to normalisation condition

$$\int w(q, p) d\Gamma = 1$$

$$\bar{u} = \int u(q, p) w(q, p) d\Gamma$$

If $f(u)$ and $g(u)$ are any two functions of u , then

$$\begin{aligned} \overline{f(u) + g(u)} &= \sum_{i=1}^M w(u_i) [f(u_i) + g(u_i)] \\ &= \sum_{i=1}^M w(u_i) f(u_i) + \sum_{i=1}^M w(u_i) g(u_i) \end{aligned}$$

Suppose we have to determine the average distance from the origin with total points N

$$\bar{x} = \frac{\sum_{i=1}^N x(i)}{N}$$

Now, if the line is divided into cells, and the distribution is given in terms of the number of points in each cell, then

$$\bar{x} = \frac{\sum_i N_i x(i)}{N}$$

$$\Rightarrow \bar{x} = \frac{\int_{-a}^a x n(x) dx}{N}$$

Noting that $\int_{-a}^a n(x) dx = N$

$$\bar{x} = \frac{\int_{-a}^a x n(x) dx}{\int_{-a}^a n(x) dx}$$

Macroscopic behaviour as an average over microscopic behaviour \bar{x} - In macroscopic point of view the thermodynamic properties remain constant but in microscopic point of view they never stay constant. one can only define the probability for the set of all possible microscopic states of the system.

The microscopic value of x is represented by $x(\alpha, P) = x(P)$ where P is the phase point. The observed value x_{obs} in macroscopic sense should be the average value of microscopic x i.e.

$$x_{obs} = \bar{x}$$

Let M is the set of all microscopic states which can be realized by the system under a given macroscopic condition and probability $d\omega$ over the volume element $d\Gamma$

$$d\omega = \int_{\Delta\Gamma} p(P) d\Gamma, \text{ where } d\Gamma = da_1 \dots da_f \cdot dr_1 \dots dr_f$$

$\Delta\Gamma$ belongs to M and p is probability density and whole phase

$$\int p d\Gamma = 1$$

$$\therefore \bar{x} = \int_M x(P) p(P) d\Gamma$$



LIUVILLE'S THEOREM

In dynamical state of a system the point in phase space is not stationary but it will move along a definite trajectory path which is determined from the equation of motion,

$$\dot{q}_i = \frac{\partial H}{\partial p_i} \quad \& \quad \dot{p}_i = -\frac{\partial H}{\partial q_i}$$

Where $H = H(q_1, \dots, q_f, p_1, \dots, p_f)$ is the Hamiltonian of the system.

As a result of this motion the density ρ of system in phase space changes with time.

In finding $\frac{\partial \rho}{\partial t}$ at a given point in phase

Liouville's made theorem - em

This theorem is primarily concerned with defining a fundamental property of the phase space - i.e. space for position & momentum space consists of two parts -

First

the conservation

$$\frac{d\rho}{dt} = 0$$

2nd Part

Phase space

of the number phase

Proof -

Consider of volume located and p_i

The

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volume

First part \circ - The first part states the conservation of density in phase space i.e.

$$\frac{d\rho}{dt} = 0.$$

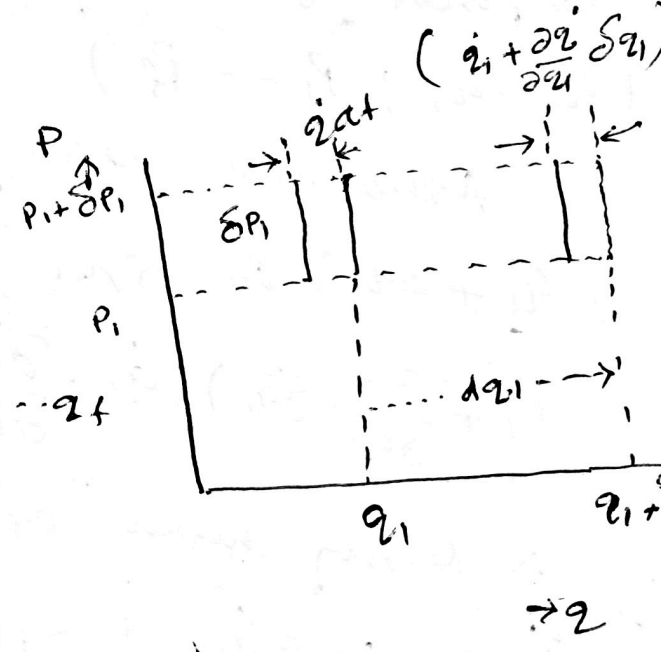
2nd part \circ - The second part gives the conservation of extension in phase space i.e.

$$\frac{d(\delta\Gamma)}{dt} = 0$$

or the volume at the disposal of a particular number of phase points is conserved through the phase space.

Proof of 1st part \circ -

Consider any fixed element of volume of phase space located betw q_1 & $q_1 + \delta q_1 \dots q_t$ and p_1 & $p_1 + \delta p_1 \dots p_t$



The no. of volume $(\delta q_1 \dots \delta q_t; \delta p_1 \dots \delta p_t)$

The change in number of systems within volume of phase space is given by

$$\left(\frac{\delta q}{\delta t}\right) dt (\delta p_1 \dots \delta p_f)$$

This change is due to the number of systems entering and leaving this volume in time dt . Let two faces of hyper volume normal to the q_1 axis with q_1 and $q_1 + \delta q_1$. Hence the no. of phase points entering the first face in time dt will be

$$p \dot{q}_1 dt (\delta q_2 \dots \delta q_f) (\delta p_1 \dots \delta p_f)$$

where p and \dot{q}_1 are the density and indicated component of velocity for representative points $(q_1 \dots q_f)$.

$$(q_1 \dots q_f; p_1 \dots p_f)$$

Again, the phase points leaving the face $(q_1 + \delta q_1)$ in time dt will be

$$\left(p + \frac{\partial p}{\partial q_1} \delta q_1\right) \left(\dot{q}_1 + \frac{\partial \dot{q}_1}{\partial q_1} \delta q_1\right) dt \delta q_2 \dots \delta q_f \delta p_1 \dots \delta p_f \quad \text{--- (1)}$$

Neglecting higher order terms, we have

$$\left[p \dot{q}_1 + \left(p \frac{\partial \dot{q}_1}{\partial q_1} + \dot{q}_1 \frac{\partial p}{\partial q_1} \right) \delta q_1 \right] dt \delta q_2 \dots \delta q_f \delta p_1 \dots \delta p_f \quad \text{--- (2)}$$

Subtracting (2) from eqn (1), we have

$$-\left(P \frac{\partial \dot{q}_i}{\partial q_i} + \dot{q}_i \frac{\partial P}{\partial q_i} \right) dt \delta q_1 \dots \delta q_n \delta p_1 \dots \delta p_n$$

Why for P_i co-ordinates, we have

$$-\left(P \frac{\partial \dot{P}_i}{\partial P_i} + \dot{P}_i \frac{\partial P}{\partial P_i} \right) dt \delta q_1 \dots \delta q_n \delta p_1 \dots \delta p_n$$

The net increase in time dt of number of system in this volume of phase space is then obtained by summing the net number of system entering the volume through all the faces labelled by $q_1 \dots q_n$ and $P_1 \dots P_n$. Then

$$\frac{d}{dt}(\delta N) = - \sum_{i=1}^f \left\{ P \left(\frac{\partial \dot{q}_i}{\partial q_i} + \frac{\partial \dot{P}_i}{\partial P_i} \right) + \left(\frac{\partial P}{\partial q_i} \dot{q}_i + \frac{\partial P}{\partial P_i} \dot{P}_i \right) \right\} dt \delta q_1 \dots \delta q_n \delta p_1 \dots \delta p_n \quad \text{--- (3)}$$

$$\text{Now } \frac{d}{dt}(\delta N) = \frac{\partial P}{\partial t} dt \delta q_1 \dots \delta q_n \delta p_1 \dots \delta p_n$$

$$\begin{aligned} \frac{\partial P}{\partial t} dt \delta q_1 \dots \delta q_n \delta p_1 \dots \delta p_n \\ = - \sum_{i=1}^f \left\{ P \left(\frac{\partial \dot{q}_i}{\partial q_i} + \frac{\partial \dot{P}_i}{\partial P_i} \right) + \left(\frac{\partial P}{\partial q_i} \dot{q}_i + \frac{\partial P}{\partial P_i} \dot{P}_i \right) \right\} dt \delta q_1 \dots \delta q_n \delta p_1 \dots \delta p_n \end{aligned}$$

$$\frac{\partial P}{\partial t} = - \sum_{i=1}^f \left\{ P \left(\frac{\partial \dot{P}_i}{\partial P_i} + \frac{\partial \dot{q}_i}{\partial q_i} \right) + \left(\frac{\partial P}{\partial q_i} \dot{q}_i + \frac{\partial P}{\partial P_i} \dot{P}_i \right) \right\} \quad \text{--- (3)}$$

The equations of motion in canonical form

$$q_i = \frac{\partial H}{\partial p_i} \quad \text{and} \quad \dot{p}_i = - \frac{\partial H}{\partial q_i}$$

$$\frac{\partial q_i}{\partial q_i} = \frac{\partial^2 H}{\partial q_i \partial p_i}$$

Since we have a set of canonical coordinates

$$\therefore \sum_{i=1}^n \left(\frac{\partial q_i}{\partial q_i} + \frac{\partial p_i}{\partial p_i} \right) = 0 \quad \text{--- (4)}$$

Substituting eq (4) in eq (3)

$$\left(\frac{\partial p}{\partial t} \right)_{z.p} = - \sum_{i=1}^n \left(\frac{\partial q_i}{\partial q_i} + \frac{\partial p_i}{\partial p_i} \right) \quad \text{--- (5)}$$

This result is known as Liouville's theorem. Hence eq (5) can be written as

$$\left(\frac{\partial p}{\partial t} \right)_{z.p} + \sum_i \frac{\partial p}{\partial q_i} \frac{dq_i}{dt} + \sum_i \frac{\partial p}{\partial p_i} \frac{dp_i}{dt} = 0 \quad \text{--- (6)}$$

and is identical with the equation of continuity in hydro-dynamics. If f is a function of z, p, t and q, p are the functions of t then

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \sum_i \frac{\partial f}{\partial q_i} \frac{dq_i}{dt} + \sum_i \frac{\partial f}{\partial p_i} \frac{dp_i}{dt}$$

generalizing this for all f 's we get

$$\sum \frac{df}{dt} = \frac{\partial f}{\partial t} + \sum_i \frac{\partial f}{\partial q_i} \frac{dq_i}{dt} + \sum_i \frac{\partial f}{\partial p_i} \frac{dp_i}{dt} \quad \text{--- (7)}$$

comparing the eqn (6) & (7) we have that

$$\frac{dp}{dt} = 0$$

This form of expression may be called the principle of the conservation of density in phase space. Therefore, the density of a group of points remains constant along their trajectory in the phase space. It will ever have uniform density.

2nd part - Since we have

$$\delta N = p \delta \Gamma$$

$$\Rightarrow \frac{d(\delta N)}{dt} = \frac{dp}{dt} \delta \Gamma + p \frac{d(\delta \Gamma)}{dt}$$

Since the number of phase points δN in a given region of the phase space must remain constant, fixed, as the system can neither be created nor destroyed, we have

have

$$\frac{d(\delta \Gamma)}{dt} = 0$$

$$\Rightarrow \frac{dp}{dt} (\delta \Gamma) + p \frac{d(\delta \Gamma)}{dt} = 0$$

We have proved that $\frac{dp}{dt} = 0$, Hence it follows that, $p \neq 0$.

$$\therefore \frac{d(\delta \Gamma)}{dt} = 0$$

This equation gives the principle of conservation of extension in phase space. //

Postulate of equal A Priori Probability

So far the methods used in st. mechanics are chiefly based on the principles of classical mechanics. In order to make applications to situations of actual interest we must now understand a consideration of the fundamental hypothesis as to equal a "PRIORI PROBABILITIES" for equal regions in phase space. This postulate doesn't arise due to any inadequacy in the principles of classical mechanics but due to the incompleteness of our knowledge concerning the systems.

As to this postulate the probability of finding the phase point for given systems in any region of the phase space is identical with that for any other region of equal extension or volume.

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